

Springs Revisited

The motion of an object with mass m on the end of a spring is given by

$$mx'' + bx' + kx = F_{ext}$$

Where m = mass of object

b = damping constant

k = spring constant

$x(t)$ = position of mass at time t

F_{ext} = external force

If $b=0$: simple harmonic motion

If $b^2 - 4mk > 0$: overdamping

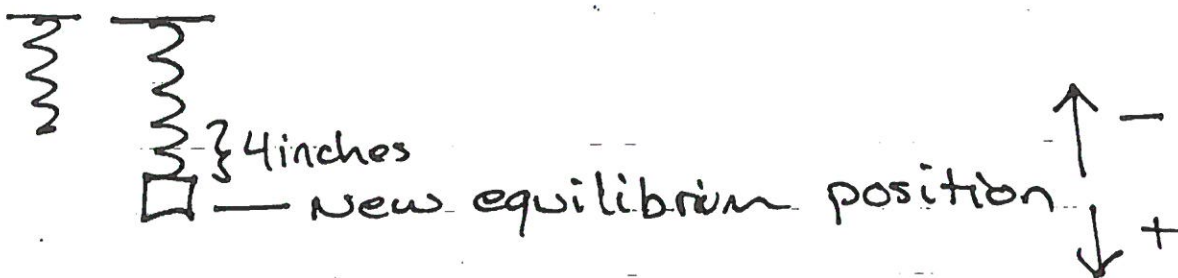
$b^2 - 4mk = 0$: critical damping

$b^2 - 4mk < 0$: underdamping

Example from Advanced Engineering Mathematics by Zill & Cullen

Ex 1 A 24-pound weight attached to the end of a spring, stretches it 4 inches. Find the equation of motion

If the weight is released from rest from a point 3 inches above the equilibrium position



$$mx'' + bx' + kx = F_{ext}$$

No damping, no external force
($b=0$) ($F_{ext}=0$)

$$mx'' + kx = 0$$

* We need to find m & k . Either they will give us a weight & we find mass or they will give us the mass outright in kg or slugs (mass units for English system)

* We know $W = 24 \text{ lb}$. From Newton's 2nd Law $F = ma \rightarrow W = mg$
OR acceleration due to gravity

Since we have English units (ft, lbs, etc)
 $g = 32 \text{ ft/s}^2$ (I will give you gravity)

$$\text{So } 24 = m 32$$

$$m = \frac{24}{32} = \frac{3}{4}$$

* Now we just need k . Unless it is just given to you, we will find it using Hooke's Law $F = kx$

F is the force stretching the spring
 x is how far it is stretched relative to the natural length.

* Weight of the object is our force

$$W = k \left(\frac{1}{3} \text{ft} \right)$$

$$4 \text{ inches} = \frac{4}{12} \text{ ft} = \frac{1}{3} \text{ ft}$$

* Remember our units need to agree lbs & ft or N & meters *

$$24 = k \frac{1}{3}$$

$$k = 72$$

$$\frac{3}{4}x'' + 72x = 0$$

* We need our initial conditions

$$x(0) = -\frac{1}{4} \text{ ft}$$

above equilibrium is negative

$$3 \text{ inches} = \frac{3}{12} = \frac{1}{4} \text{ ft}$$

$$x'(0) = 0$$

released from rest means no initial velocity

If we were just asked to formulate the IVP

$$\boxed{\begin{array}{l} \frac{3}{4}x'' + 72x = 0 \quad x(0) = -\frac{1}{4} \\ x'(0) = 0 \end{array}}$$

For this first one we'll solve it all the way:

Characteristic equation

$$\frac{3}{4}r^2 + 72 = 0$$

$$r^2 = -\frac{72(4)}{3}$$

$$r^2 = -24(4)$$

$$r = \pm \sqrt{-24 \cdot 4}$$

$$= \pm \sqrt{-4 \cdot 6 \cdot 4}$$

$$= \pm 4\sqrt{-6}$$

$$= \pm 4\sqrt{6}i$$

Case 3 →

$$\alpha = 0 \quad \beta = 4\sqrt{6}$$

$$x(t) = e^{0t} [C_1 \cos(4\sqrt{6}t) + C_2 \sin(4\sqrt{6}t)]$$

$$x(t) = C_1 \cos(4\sqrt{6}t) + C_2 \sin(4\sqrt{6}t)$$

$$x(0) = -1/4 = C_1 \cos 0 + C_2 \sin 0$$

$$C_1 = -1/4$$

$$x(t) = -\frac{1}{4} \cos(4\sqrt{6}t) + C_2 \sin(4\sqrt{6}t)$$

$$x'(t) = -\frac{1}{4}(-\sin(4\sqrt{6}t)4\sqrt{6}) + 4\sqrt{6}C_2 \cos(4\sqrt{6}t)$$

$$x'(t) = \sqrt{6} \sin(4\sqrt{6}t) + 4\sqrt{6}C_2 \cos(4\sqrt{6}t)$$

$$x'(0) = \sqrt{6} \sin 0 + 4\sqrt{6}C_2 \cos 0 = 0$$

$$C_2 = 0$$

$$\rightarrow \boxed{x(t) = -\frac{1}{4} \cos(4\sqrt{6}t)}$$

Simple harmonic motion, $b=0$

Examples from Differential Equations
by Brannan & Boyce

Ex 2 A mass of 1 kg stretches a spring 5 cm. If the mass is set in motion from its equilibrium position with a downward velocity of 10 cm/s, and if

there is no damping, determine the position x of the mass at time t .

Again $b=0$, $F_{ext}=0$

$$mx'' + kx = 0$$

We know $m = .1 \text{ kg}$, we just need to find k using $F=kx$.

The force that stretches the spring is the weight of the object

$$W = kx$$

$$mg = kx$$

$$.1(9.8 \text{ m/s}^2) = k(.05 \text{ m})$$

$5 \text{ cm} = .05 \text{ m}$

gravity if we are using the metric system

$$.98 = k \frac{5}{100}$$

$$\frac{98}{5} = k$$

equilibrium

$$\begin{aligned} .1x'' + \frac{98}{5}x &= 0 & x(0) &= 0 \\ & & x'(0) &= .1 \text{ m/s} \end{aligned}$$

IVP describing motion of mass

downward velocity + $10 \text{ cm/s} = .1 \text{ m/s}$

$$\bullet \text{ } 1r^2 + \frac{98}{5} = 0$$

$$r^2 = -\frac{980}{5} = -196$$

$$r = \pm \sqrt{-196} = \pm 14i \quad \begin{matrix} \alpha=0 \\ \beta=14 \end{matrix}$$

$$X(t) = e^{0t} [C_1 \cos(14t) + C_2 \sin(14t)]$$

$$X(t) = C_1 \cos(14t) + C_2 \sin(14t)$$

$$\begin{aligned} X(0) = 0 &= C_1 \cos 0 + C_2 \sin 0 \\ &= C_1 \cdot 1 \\ C_1 &= 0 \end{aligned}$$

$$X(t) = C_2 \sin(14t)$$

$$X'(t) = 14 C_2 \cos(14t)$$

$$\begin{aligned} X'(0) = 14 C_2 &= 1 \\ C_2 &= 1/14 = 1/140 \end{aligned}$$

$$X(t) = \frac{1}{140} \sin(14t)$$

Ex 3 A mass weighing 16 lb stretches a spring 3 in. The mass is attached to a viscous damper with a damping constant of 2. If the mass is set in motion from its equilibrium position with a downward velocity of 3 inches/sec find its position $x(t)$ at time t . Determine when the mass first returns to its equilibrium position

$$mx'' + bx' + kx = F \sin t$$

$$W = 16 \text{ lb} = mg \quad \leftarrow \text{they gave us weight we need mass}$$

$$16 = m(32)$$

$$m = \frac{16}{32} = \frac{1}{2}$$

$$b = 2 \quad \leftarrow \text{they gave this to us}$$

* still need k

$$F = kx$$

$$W = 16 = k \left(\frac{1}{4}\right)$$

$$3 \text{ inches} = \frac{1}{4} \text{ ft}$$

$$k = 64$$

IVP describing motion of mass P9

$$\frac{1}{2}x'' + 2x' + 64x = 0$$

$$x(0) = 0$$

$$x'(0) = \frac{1}{4} \text{ ft/s}$$

3 inches/s

* Remember downward = positive
 upward = negative
 likewise compression = negative
 stretch = positive

$$\frac{1}{2}r^2 + 2r + 64 = 0$$

$$r^2 + 4r + 128 = 0$$

$$r = \frac{-4 \pm \sqrt{16 - 4(128)}}{2}$$

$$= \frac{-4 \pm \sqrt{16 - 4(4 \cdot 32)}}{2}$$

$$= \frac{-4 \pm \sqrt{16 - 16 \cdot 32}}{2}$$

$$= \frac{-4 \pm \sqrt{16(1 - 32)}}{2}$$

$$= \frac{-4 \pm 4\sqrt{-31}}{2} = -2 \pm 2\sqrt{31}i$$

$b^2 - 4mk < 0$
 Underdamping
 lots of oscillations

$$X(t) = e^{-2t} [C_1 \cos(2\sqrt{3}t) + C_2 \sin(2\sqrt{3}t)]$$

$$X(0) = 0 \rightarrow C_1 = 0$$

$$X(t) = e^{-2t} C_2 \sin(2\sqrt{3}t)$$

$$X'(t) = -2e^{-2t} C_2 \sin(2\sqrt{3}t) + e^{-2t} C_2 2\sqrt{3} \cos(2\sqrt{3}t)$$

$$X'(0) = -2 \cdot C_2 \cdot 0 + C_2 2\sqrt{3} = \frac{1}{4}$$

$$C_2 = \frac{1}{8\sqrt{3}}$$

$$X(t) = \frac{1}{8\sqrt{3}} e^{-2t} \sin(2\sqrt{3}t)$$

When will the mass return to equilibrium?

$$X(t) = 0 = \frac{1}{8\sqrt{3}} e^{-2t} \sin(2\sqrt{3}t)$$

All we need is to know when $\sin(2\sqrt{3}t) = 0$ since the rest is never zero.

Obviously $t=0$ works, this makes sense since we are starting from equilibrium

We just want the next value of t that will work:

$$\sin 0 = 0, \sin \pi = 0, \sin 2\pi, \text{ etc}$$

\uparrow next value to give us zero

When does $2\sqrt{3}l t = \pi$?

$$t = \frac{\pi}{2\sqrt{3}l}$$

time to return to equilibrium.

