

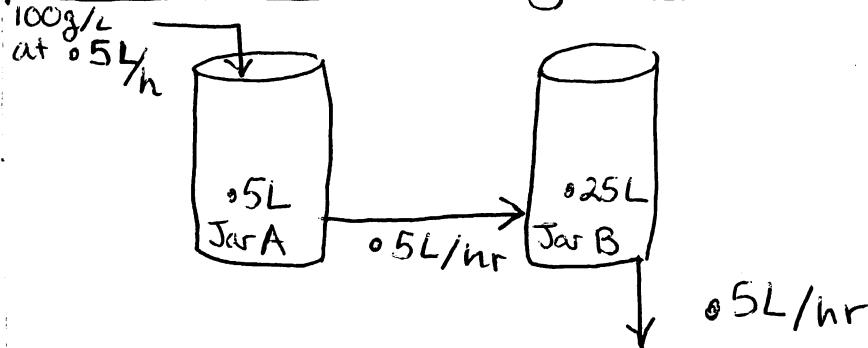
P1

MIXING PROBLEMS WITH INTERCONNECTED TANKS

* These problems build on our knowledge of mixing problems with a single tank and our recent work with matrices.

Examples from Introduction to Differential Equations
by Campbell & Haberman
p377-379

Ex 1 Two jars are initially full of pure water. Jar A is 0.5L and Jar B is 0.25L. Water containing salt at a concentration of 100 g/L is pumped into jar A at 0.5L/h. Water flows from jar A to jar B at 0.5L/h. Water flows out of jar B and down a drain at 0.5 L/h. Find the amount of salt in each jar at time t.



Initial conditions:
 $X_1(0) = 0$ } *They told us
 $X_2(0) = 0$ } we started
with pure water*

Let $X_1(t)$ be the amount of salt in jar A at time t
 $X_2(t)$ be the amount of salt in jar B at time t

P2

Then $\frac{dx_1}{dt}$ and $\frac{dx_2}{dt}$ represent how the amount of salt in jar A and jar B change as time passes.

$$\frac{dx_1}{dt} = \text{Input rate} - \text{Output rate}$$

$$= (\text{Concentration}_{\text{in}}) (\text{flow rate}_{\text{in}}) - (\text{Concentration}_{\text{out}}) (\text{flow rate}_{\text{out}})$$

$$= \left(\frac{100\text{g}}{\text{L}} \right) \left(\frac{0.5\text{L}}{\text{hr}} \right) - \left(\frac{x_1}{0.5\text{L}} \right) \left(\frac{0.5\text{L}}{\text{hr}} \right)$$

Concentration out is the amount of salt in jar A divided by the amount of liquid in jar A.
 $x_1(t)$ = salt in jar A
and 0.5L is the amount of liquid

$$\frac{dx_2}{dt} = \left(\frac{x_1}{0.5\text{L}} \right) \left(\frac{0.5\text{L}}{\text{hr}} \right) - \left(\frac{x_2}{0.25\text{L}} \right) \left(\frac{0.5\text{L}}{\text{hr}} \right)$$

x_2 = amount of salt in jar B
 0.25 = volume of jar B

Simplifying: $\frac{dx_1}{dt} = 50 - x_1$

$$\frac{dx_2}{dt} = x_1 - 2x_2$$

* We can represent this using matrices -- this is useful since we can solve this using our matrix techniques

P3

We want to represent it using

$$\vec{x}' = A \vec{x} + \vec{f} \quad \vec{x}(0) = \vec{x}_0$$

Our system of equations has 2 derivatives, $\frac{dx_1}{dt}$ and $\frac{dx_2}{dt}$; these will become our \vec{x}' ,

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}' = \begin{pmatrix} \frac{dx_1}{dt} \\ \frac{dx_2}{dt} \end{pmatrix}$$

Once we have our \vec{x}' , we automatically have our \vec{x}

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}' = A \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \vec{f}$$

A is a matrix that contains the coefficients of x_1 and x_2

* For $\frac{dx_1}{dt} = 50 - x_1$ the coefficient of x_1 is -1 , the coefficient of x_2 is 0 (because there isn't an x_2)

Whatever is left over belongs to \vec{f} , in this case it is 50 .

* For $\frac{dx_2}{dt} = x_1 - 2x_2$ the coefficient of

x_1 is 1 and for x_2 it is -2 , and there isn't anything leftover for \vec{f}

P4

So our $A = \begin{pmatrix} -1 & 0 \\ 1 & -2 \end{pmatrix}$ and $\vec{f} = \begin{pmatrix} 50 \\ 0 \end{pmatrix}$

* You'll know that you found the correct values of A and \vec{f} if when you multiply everything out you get our original system

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}' = \begin{pmatrix} -1 & 0 \\ 1 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} 50 \\ 0 \end{pmatrix}$$

Double checking: $\begin{pmatrix} x_1' \\ x_2' \end{pmatrix} = \begin{pmatrix} -1x_1 + 0x_2 \\ 1x_1 - 2x_2 \end{pmatrix} + \begin{pmatrix} 50 \\ 0 \end{pmatrix}$

$$\begin{pmatrix} x_1' \\ x_2' \end{pmatrix} = \begin{pmatrix} -x_1 + 50 \\ x_1 - 2x_2 \end{pmatrix} \quad \checkmark$$

* For a test you will just set up the problem so your final answer would be?

$$\boxed{\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}' = \begin{pmatrix} -1 & 0 \\ 1 & -2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} 50 \\ 0 \end{pmatrix}}$$
$$\vec{x}(0) = \begin{pmatrix} x_1(0) \\ x_2(0) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

* This problem looks like it might be pleasant so let's work it out for extra practice

P5

$$A = \begin{pmatrix} -1 & 0 \\ 1 & -2 \end{pmatrix}$$

* 1st we need \vec{x}_c and to find that we need the eigenvalues and eigenvectors of A

Eigenvalues: $|A - rI| = 0$

$$\begin{vmatrix} -1-r & 0 \\ 1 & -2-r \end{vmatrix} = (-1-r)(-2-r) - 0(1) = 0$$

$$\text{or } (-1-r)(-2-r) = 0$$

$r_1 = -1 \quad r_2 = -2$ are our eigenvalues

Eigenvectors: $(A - rI)\vec{u} = \vec{0}$

$$r_1 = -1: \quad (A - (-1)I)\vec{u} = \vec{0}$$

$$\begin{pmatrix} 0 & 0 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$u_1 - u_2 = 0 \quad u_1 = u_2 \quad \boxed{\vec{u}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \text{ 1st eigenvector}}$$

$$r_2 = -2: \quad (A - (-2)I)\vec{u} = \vec{0}$$

$$\begin{pmatrix} 1 & 0 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

so $u_1 = 0$, u_2 has no restrictions

so $\vec{u}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$

$$\boxed{\vec{x}_c = c_1 e^{-t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + c_2 e^{-2t} \begin{pmatrix} 0 \\ 1 \end{pmatrix}}$$

* Now we need \vec{x}_p . Let's find it using our Variation of Parameters method

$$\vec{x}_p = \vec{X} S \vec{X}^{-1} \vec{f}$$

* We need \vec{X} the fundamental matrix; remember we get that from \vec{x}_c

$$\vec{x}_c = c_1 e^{-t} \begin{pmatrix} 1 \\ 1 \end{pmatrix} + c_2 e^{-2t} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\text{so } \vec{X} = \begin{pmatrix} e^{-t} & 0e^{-2t} \\ 1e^{-t} & 1e^{-2t} \end{pmatrix} = \begin{pmatrix} e^{-t} & 0 \\ e^{-t} & e^{-2t} \end{pmatrix}$$

* Let's use our formula for the inverse of a 2×2 matrix

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \quad A^{-1} = \frac{1}{ad - bc} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$$

When A^{-1} exists

$$\begin{aligned} \text{so } \vec{X}^{-1} &= \frac{1}{e^{-t} e^{-2t} - 0e^{-t}} \begin{pmatrix} e^{-2t} & 0 \\ -e^{-t} & e^{-t} \end{pmatrix} \\ &= e^{3t} \begin{pmatrix} e^{-2t} & 0 \\ -e^{-t} & e^{-t} \end{pmatrix} = \begin{pmatrix} e^t & 0 \\ -e^{2t} & e^{2t} \end{pmatrix} \end{aligned}$$

$$\begin{aligned} \vec{x}_p &= \vec{X} S \vec{X}^{-1} \vec{f} = \vec{X} S \begin{pmatrix} e^t & 0 \\ -e^{2t} & e^{2t} \end{pmatrix} \begin{pmatrix} 50 \\ 0 \end{pmatrix} \\ &= \vec{X} S \begin{pmatrix} 50e^t \\ -50e^{2t} \end{pmatrix} dt = \begin{pmatrix} e^t & 0 \\ e^t & e^{-2t} \end{pmatrix} \begin{pmatrix} 50e^t \\ -\frac{50}{2}e^{2t} \end{pmatrix} \\ &= \begin{pmatrix} 50 \\ 50-25 \end{pmatrix} = \begin{pmatrix} 50 \\ 25 \end{pmatrix} \end{aligned}$$

P7

So our general solution is

$$\vec{X} = \vec{X}_c + \vec{X}_p$$

$$\boxed{\vec{X} = c_1 e^{-t}(1) + c_2 e^{-2t}(1) + \begin{pmatrix} 50 \\ 25 \end{pmatrix}}$$

* But we have ... initial conditions

$\vec{X}(0) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$, so we can use the general solution to solve for c_1 and c_2 .

$$\vec{X}(0) = c_1 e^{-0}(1) + c_2 e^{-2(0)}(1) + \begin{pmatrix} 50 \\ 25 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$c_1(1) + c_2(1) + \begin{pmatrix} 50 \\ 25 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$c_1 + 50 = 0 \quad c_1 = -50$$

$$c_1 + c_2 + 25 = 0 \rightarrow c_2 = 25$$

Final answer:

$$\vec{X} = -50e^{-t}(1) + 25e^{-2t}(1) + \begin{pmatrix} 50 \\ 25 \end{pmatrix}$$

or

$$\vec{X} = \begin{pmatrix} -50e^{-t} + 50 \\ -50e^{-t} + 25e^{-2t} + 25 \end{pmatrix}$$

$$\text{So } x_1(t) = -50e^{-t} + 50$$

and

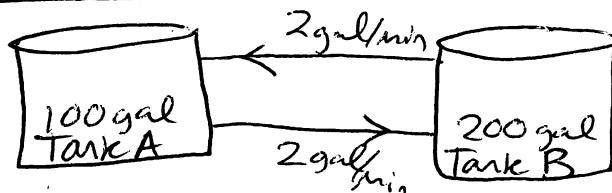
$$x_2(t) = -50e^{-t} + 25e^{-2t} + 25$$

Note: as $t \rightarrow \infty$ $x_1 \rightarrow 50$ g of salt and $x_2 \rightarrow 25$ g of salt

Ex 2

There are 2 tanks. Tank A is a 100-gal tank, initially full of water containing salt at a concentration of 0.5 lb/gal. Tank B is a 200-gal tank, initially full of water containing salt at a concentration of 0.11 lb/gal. Starting at time $t=0$, water is pumped from tank A to tank B at 2 gal/min and from tank B to tank A at 2 gal/min. If $\vec{x}_1(t)$ is the amount of salt in tank A and $\vec{x}_2(t)$ is the amount of salt in tank B at time t , find A , \vec{f} , and \vec{x}_0 so that

$$\begin{pmatrix} \dot{x}_1 \\ \dot{x}_2 \end{pmatrix} = A \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \vec{f} \quad \vec{x}(0) = \vec{x}_0$$



$$\text{Concentration} = \frac{\text{amount}}{\text{volume}} = \frac{x_1(0)}{100} = 0.5 \text{ lb/gal}$$

$$x_1(0) = 50 \text{ lb}$$

$$\text{Concentration} = \frac{x_2(0)}{200} = 0.11 \text{ lb/gal}$$

$$x_2(0) = 22 \text{ lb}$$

$$\frac{dx_1}{dt} = \left(\frac{x_2}{200}\right)\left(\frac{2 \text{ gal}}{\text{min}}\right) - \left(\frac{x_1}{100}\right)\left(\frac{2 \text{ gal}}{\text{min}}\right)$$

$$\frac{dx_1}{dt} = \frac{x_2}{100} - \frac{x_1}{50}$$

$$\frac{dx_2}{dt} = \left(\frac{x_1}{100} \right) \left(\frac{2 \text{ gal}}{\text{min}} \right) - \left(\frac{x_2}{200} \right) \left(\frac{2 \text{ gal}}{\text{min}} \right)$$

$$\frac{dx_2}{dt} = \frac{x_1}{50} - \frac{x_2}{100}$$

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix}' = \begin{pmatrix} -\frac{1}{50} & \frac{1}{100} \\ \frac{1}{100} & \frac{1}{50} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$\uparrow A \quad \uparrow \vec{f}$

$$\vec{x}(0) = \begin{pmatrix} 50 \\ 20 \end{pmatrix}$$

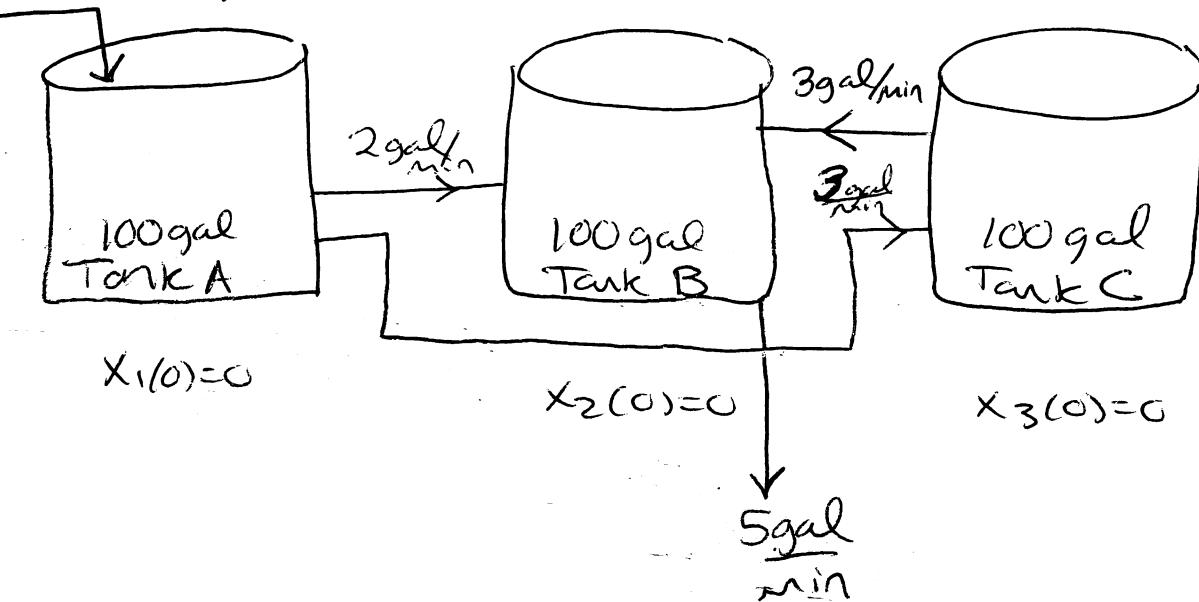
Ex 3 There are 3 tanks, each initially containing 100 gal of pure water.

Water containing salt at a concentration of 2 lb/gal flows into tank A at a rate of 5 gal/min. Water is pumped from tank A to tank B at 2 gal/min and from tank A to tank C at 3 gal/min. Water is pumped from tank C to tank B at 3 gal/min. Water is pumped out of tank B and then down a drain at a rate of 5 gal/min.

If $x_1(t)$, $x_2(t)$, and $x_3(t)$ are the amounts of salt in tank A, tank B, and tank C respectively, find A , \vec{f} , and \vec{x}_0 so that

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}' = A \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} + \vec{f} \quad \vec{x}(0) = \vec{x}_0$$

21b/gal at 5gal/min



$$\frac{dx_1}{dt} = \left(2 \frac{\text{lb}}{\text{gal}}\right)\left(\frac{5\text{gal}}{\text{min}}\right) - \left(\frac{x_1}{100\text{gal}}\right)\left(\frac{2\text{gal}}{\text{min}}\right) - \left(\frac{x_1}{100\text{gal}}\right)\left(\frac{3\text{gal}}{\text{min}}\right)$$

$$\frac{dx_1}{dt} = 10 - \frac{5x_1}{100} = 10 - \frac{x_1}{20}$$

$$\frac{dx_2}{dt} = \left(\frac{x_1}{100\text{gal}}\right)\left(\frac{2\text{gal}}{\text{min}}\right) + \left(\frac{x_3}{100\text{gal}}\right)\left(\frac{3\text{gal}}{\text{min}}\right) - \left(\frac{x_2}{100\text{gal}}\right)\left(\frac{5\text{gal}}{\text{min}}\right)$$

$$\frac{dx_2}{dt} = \frac{x_1}{50} + \frac{3x_3}{100} - \frac{x_2}{20}$$

$$\frac{dx_3}{dt} = \left(\frac{x_1}{100\text{gal}}\right)\left(\frac{3\text{gal}}{\text{min}}\right) - \left(\frac{x_3}{100\text{gal}}\right)\left(\frac{3\text{gal}}{\text{min}}\right)$$

$$\frac{dx_3}{dt} = \frac{3x_1}{100} - \frac{3x_3}{100}$$

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}' = \begin{pmatrix} -\frac{1}{20} & 0 & 0 \\ \frac{1}{50} & -\frac{1}{20} & \frac{3}{100} \\ \frac{3}{100} & 0 & -\frac{3}{100} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} + \begin{pmatrix} 10 \\ 0 \\ 0 \end{pmatrix}$$

$\vec{x}(0) = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$	$A = \begin{pmatrix} -\frac{1}{20} & 0 & 0 \\ \frac{1}{50} & -\frac{1}{20} & \frac{3}{100} \\ \frac{3}{100} & 0 & -\frac{3}{100} \end{pmatrix}$	$\vec{f} = \begin{pmatrix} 10 \\ 0 \\ 0 \end{pmatrix}$
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